

Jeti as primary back-channel

Non compensated vario

Recommended as **starting** set for GPS Light class

Sparrow can be replaced with Swift

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **non-compensated**: On Jeti transmitter as Ex sensor value or/and on Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



Jeti as primary back-channel

Non compensated vario

Recommended as **advance** set for GPS Light class

Sparrow can be replaced with Swift

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **non-compensated**: On Snipe audio output and/or on Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

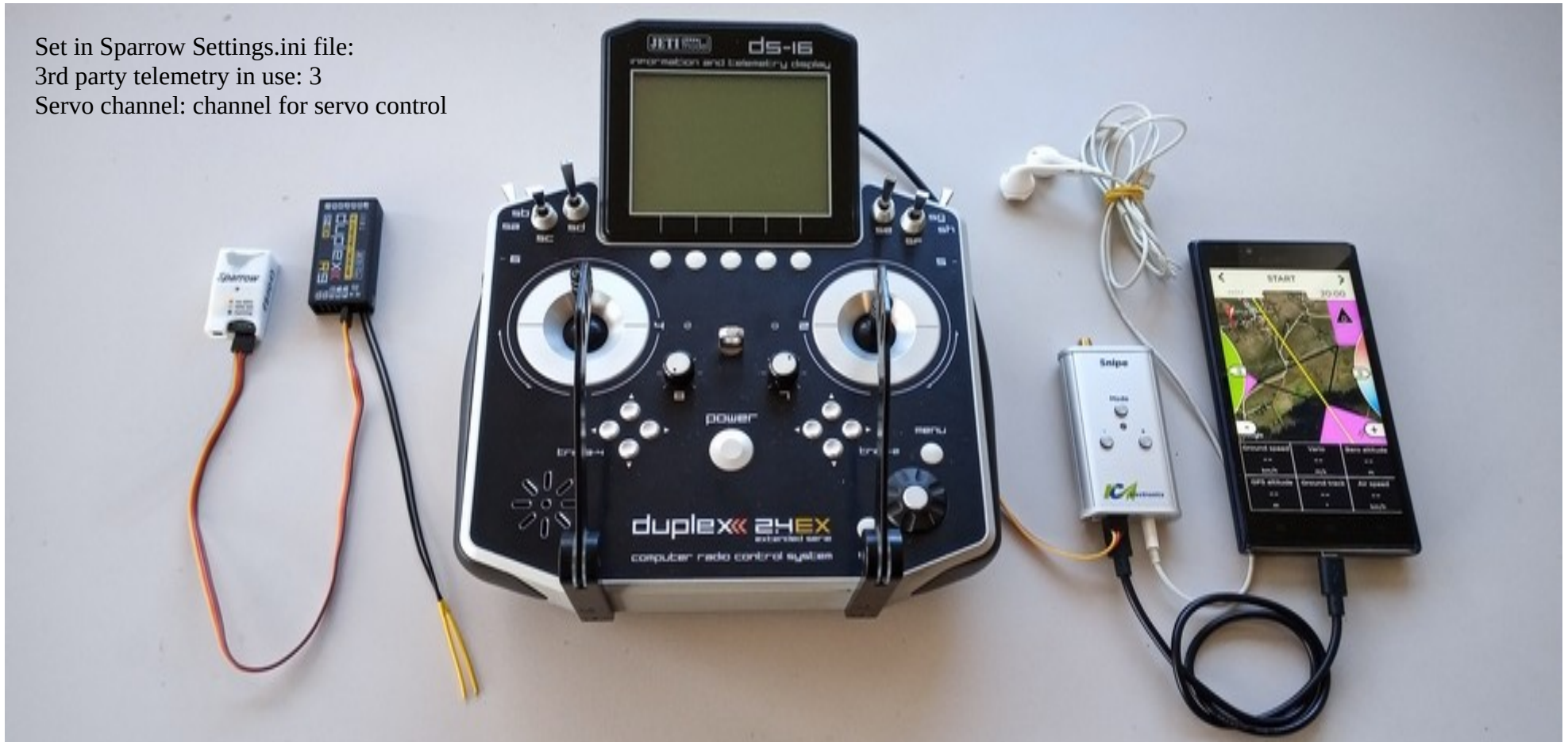
Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



Jeti as primary back-channel Compensated vario

Recommended as **basic** set for GPS Sport class

Swift is recommended for sport class!

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **compensated**: On Jeti transmitter as Ex sensor value or/and in Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

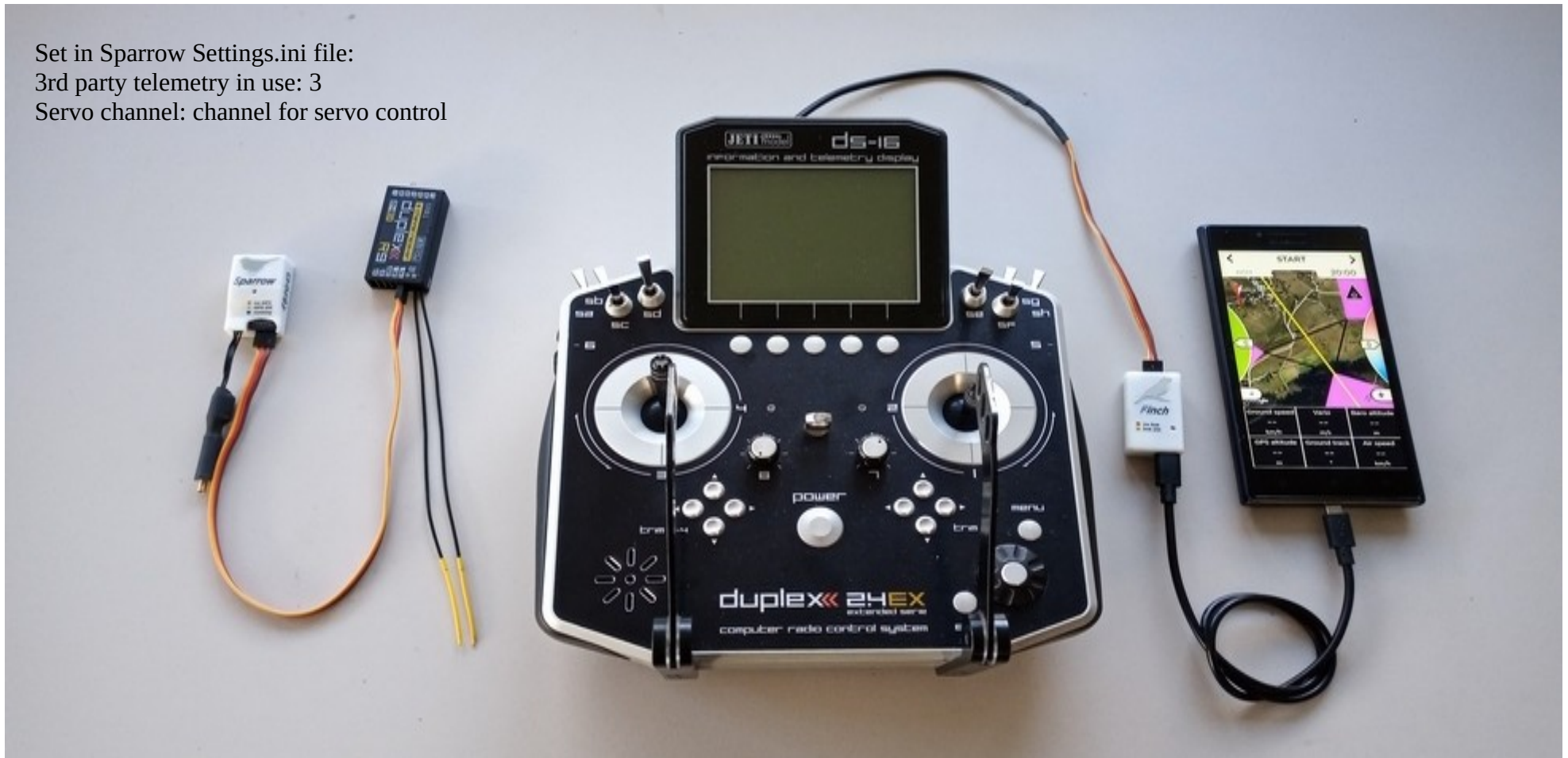
Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



Jeti as primary back-channel

Compensated vario

Recommended as **advance** set for GPS Sport class

Swift is recommended for sport class!

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **compensated**: On Snipe audio output and/or on Abatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



Jeti as secondary back-channel
Compensated vario
RF module for primary RF link

Recommended as **pro** set for GPS Sport class

Swift is recommended for sport class!

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **compensated**: On Snipe audio output and/or on Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

2nd RF link: yes, faster refresh rate and more stable link

Set on Jeti PPM output connector: EX Data Stream
On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe



Jeti as secondary back-channel

Compensated vario

RF module for primary RF link

Recommended as **pro** set for GPS scale and SLS class

Jeti Cable is required and is installed inside Jeti transmitter!

Vario **compensated**: On Snipe audio output and/or Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning, **stall**, **speed**

Beeps: yes

MacCready flying: **yes**

Servo control in Albatross: yes

2nd RF link: yes, faster refresh rate and more stable link

Polar measurement: yes

Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

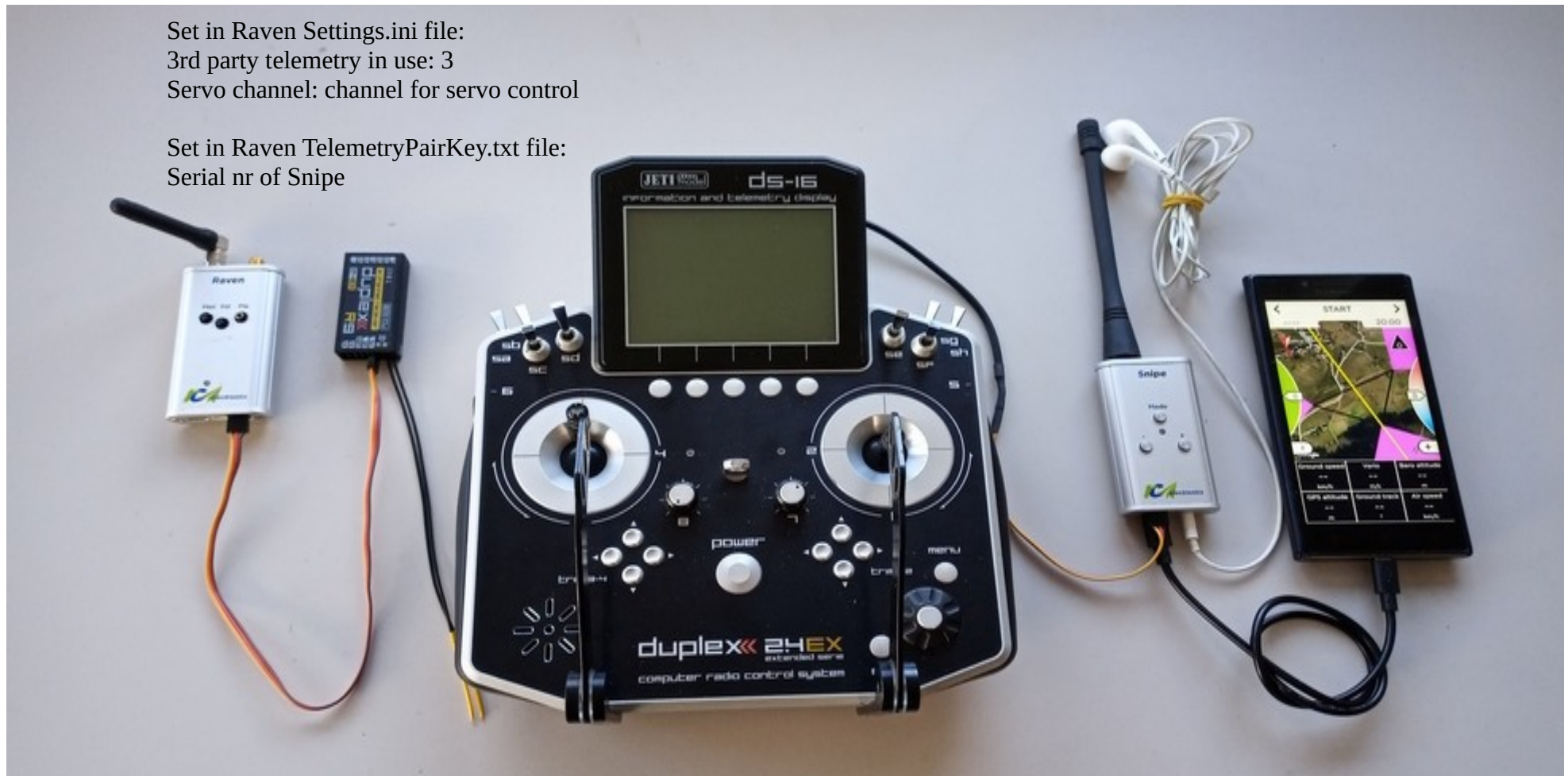
Set in Raven Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control

Set in Raven TelemetryPairKey.txt file:

Serial nr of Snipe



System independent configuration

Non compensated vario

Recommended as **starting** set for GPS Light class

Sparrow can be replaced with Swift

Vario **non-compensated**: vario beep in Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Finch



System independent configuration

Non compensated vario

Recommended as **advance** set for GPS Light class

Sparrow can be replaced with Swift

Vario **non-compensated**: On Snipe audio output and/or on Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe



System independent configuration

Compensated vario

Recommended as **basic** set for GPS Sport class

Swift is recommended for sport class!

Vario **compensated**: vario beep in Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Finch



System independent configuration

Compensated vario

Recommended as **advance** set for GPS Sport class

Recommended as **basic** set for GPS Scale and SLS class

Swift is recommended for sport class and Scale / SLS!

Vario **compensated**: On Snipe audio output and/or on Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe



System independent configuration

Compensated vario

Recommended as **pro** set for GPS Scale and SLS class

Vario **compensated**: On Snipe audio output and / or Albatross

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning, **stall**, **speed**

Beeps: yes

MacCready flying: **yes**

Servo control in Albatross: yes

Polar measurement: yes

Set in Raven Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Raven TelemetryPairKey.txt file:

Serial nr of Snipe



System independent T3000 configuration Compensated vario

Older system which is not available anymore. Due to GPS rules it is allowed only in scale class with no motor as Multi 2 system cannot detect motor.

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control for Start/restart: yes

Polar measurement: no



System independent T3000 configuration Compensated vario + Albatross

Older system which is not available anymore. Due to GPS rules it is allowed only in scale class with no motor as Multi 2 system cannot detect motor.

T3000 cable is used for connection to Albatross

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in Albatross: yes

Polar measurement: no



System independent T3000 configuration

Compensated vario

Recommended for all: Light, Scale and SLS class

T3000 requires v 3.x to work with Sparrow, Swift, Raven!

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in for Start/restart: yes

Polar measurement: no

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of T3000



System independent T3000 configuration

Compensated vario + Albatross

Recommended for all: Light, Scale and SLS class

T3000 requires v 3.x to work with Sparrow, Swift, Raven!

T3000 cable is used for connection to Albatross

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in for Start/restart: yes

Polar measurement: no

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of T3000



System independent T3000 configuration

Compensated vario

Recommended for all: Scale and SLS class

T3000 requires v 3.x to work with Sparrow, Swift, Raven!

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control for Start/restart: yes

Polar measurement: yes

Set in Raven Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Raven TelemetryPairKey.txt file:

Serial nr of T3000



System independent T3000 configuration

Compensated vario + Albatross

Recommended for all: Scale and SLS class

T3000 requires v 3.x to work with Sparrow, Swift, Raven!

T3000 cable is used for connection to Albatross

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in Albatross: yes

Polar measurement: yes

Airspeed indicator in Albatross: yes

Set in Raven Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

Connect servo lead to bottom connector!

Set in Raven TelemetryPairKey.txt file:

Serial nr of T3000



Core as primary link + Albatross

Works for all classes

Swift is used as example on picture, but Sparrow or Raven can be used also.

Finch can be replaced with Snipe to get stereo audio navigation

Vario **compensated** / **non compensated** (depends if TEK sensor is used): On Core audio or /and on Albatross

Stereo navigation: yes if Snipe is used instead of Finch

Voices: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no** (yes in case of Raven + Snipe)

Servo control in Albatross: yes

Polar measurement: yes

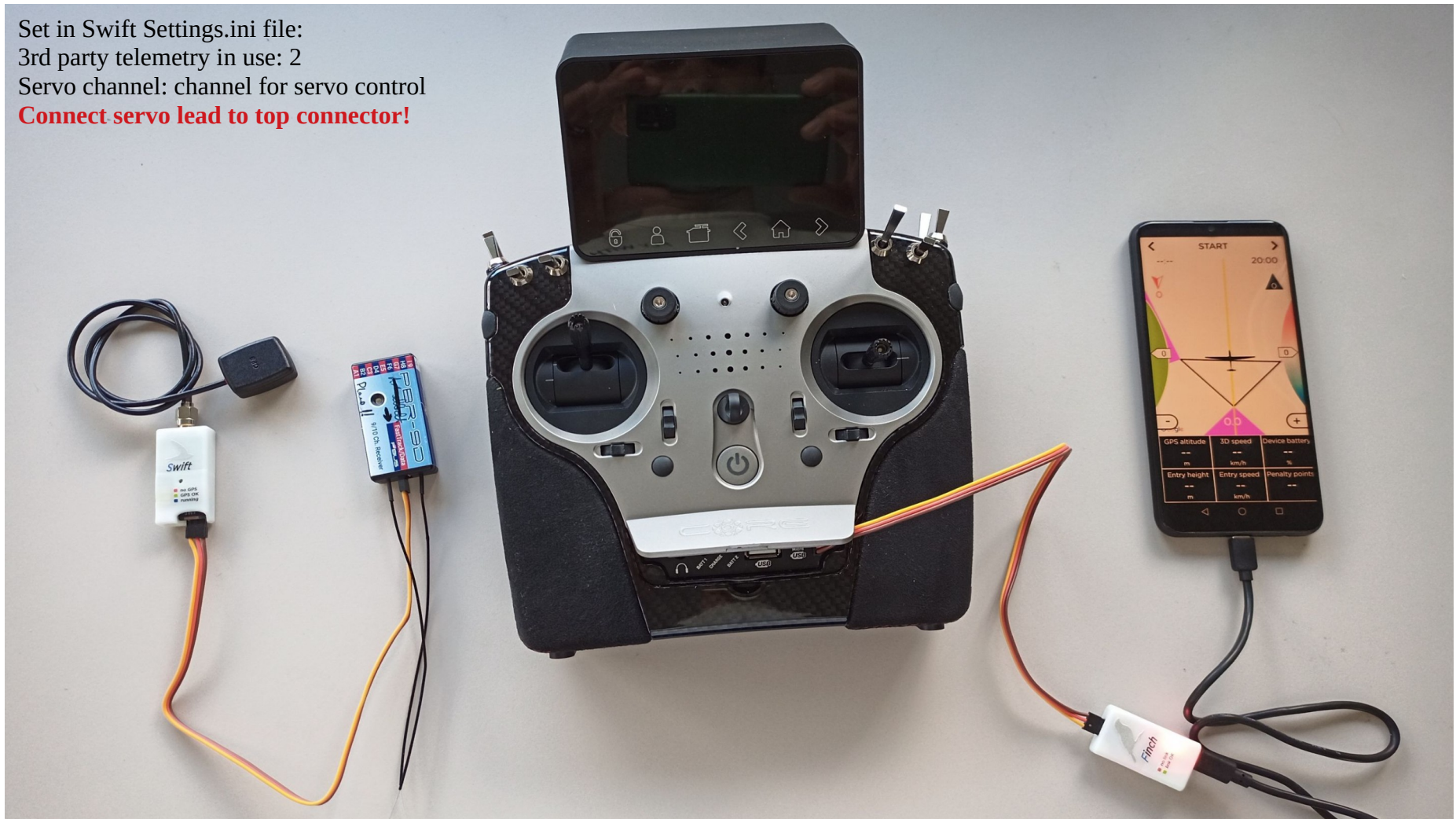
Airspeed indicator in Albatross: yes in case of Raven

Set in Swift Settings.ini file:

3rd party telemetry in use: 2

Servo channel: channel for servo control

Connect servo lead to top connector!



Core as primary link + PBR receiver + Albatross

Works for all classes. With PBR receiver Albatross tablet/phone can be on a stand and pilot can move around. It is also possible to have dual system with one Albatross connected to Core and one to PBR for a helper.

Swift is used as example on picture, but Sparrow or Raven can be used also.

Finch can be replaced with Snipe to get stereo audio navigation

Vario **compensated** / **non compensated** (depends if TEK sensor is used): On Core audio or /and on Albatross

Stereo navigation: yes if Snipe is used instead of Finch

Voices: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no** (yes in case of Raven + Snipe)

Servo control in Albatross: yes

Polar measurement: yes

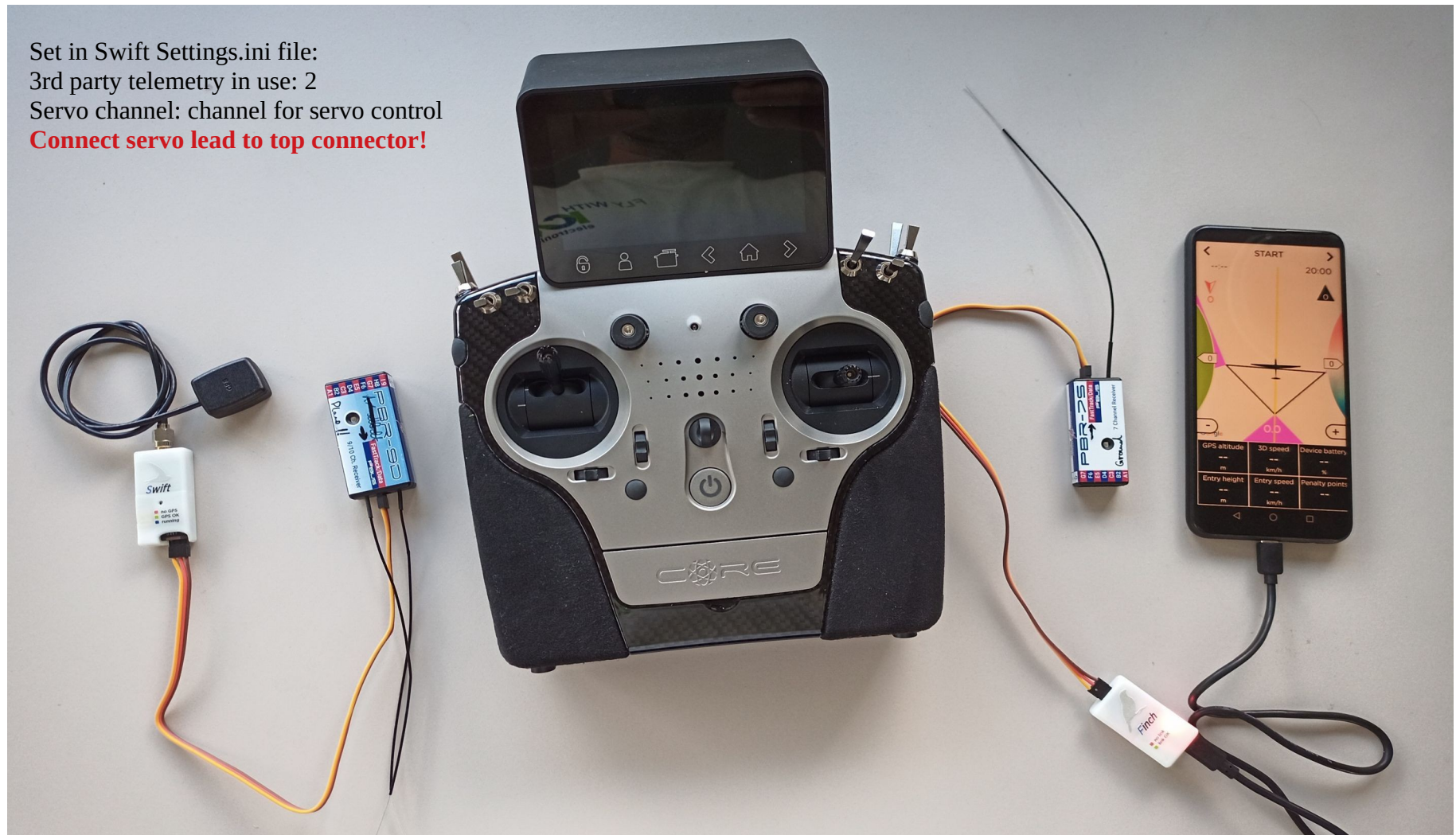
Airspeed indicator in Albatross: yes in case of Raven

Set in Swift Settings.ini file:

3rd party telemetry in use: 2

Servo channel: channel for servo control

Connect servo lead to top connector!



Core as 2nd link + Albatross

Works for all classes. User can add PBR receiver as 2nd link receiver. See example above.

It is also possible to have dual system with one Albatross connected to Core and one to PBR for a helper.

Raven is used as example on picture, but Sparrow or Swift can be used also.

Snipe can be replaced with Finch.

Vario **compensated** / **non compensated** (depends if TEK sensor is used): On Core audio or /and on Albatross

Stereo navigation: yes if Snipe is used instead of Finch

Voices: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no** (yes in case of Raven + Snipe)

Servo control in Albatross: yes

Polar measurement: yes

Airspeed indicator in Albatross: yes in case of Raven

Set in Raven Settings.ini file:

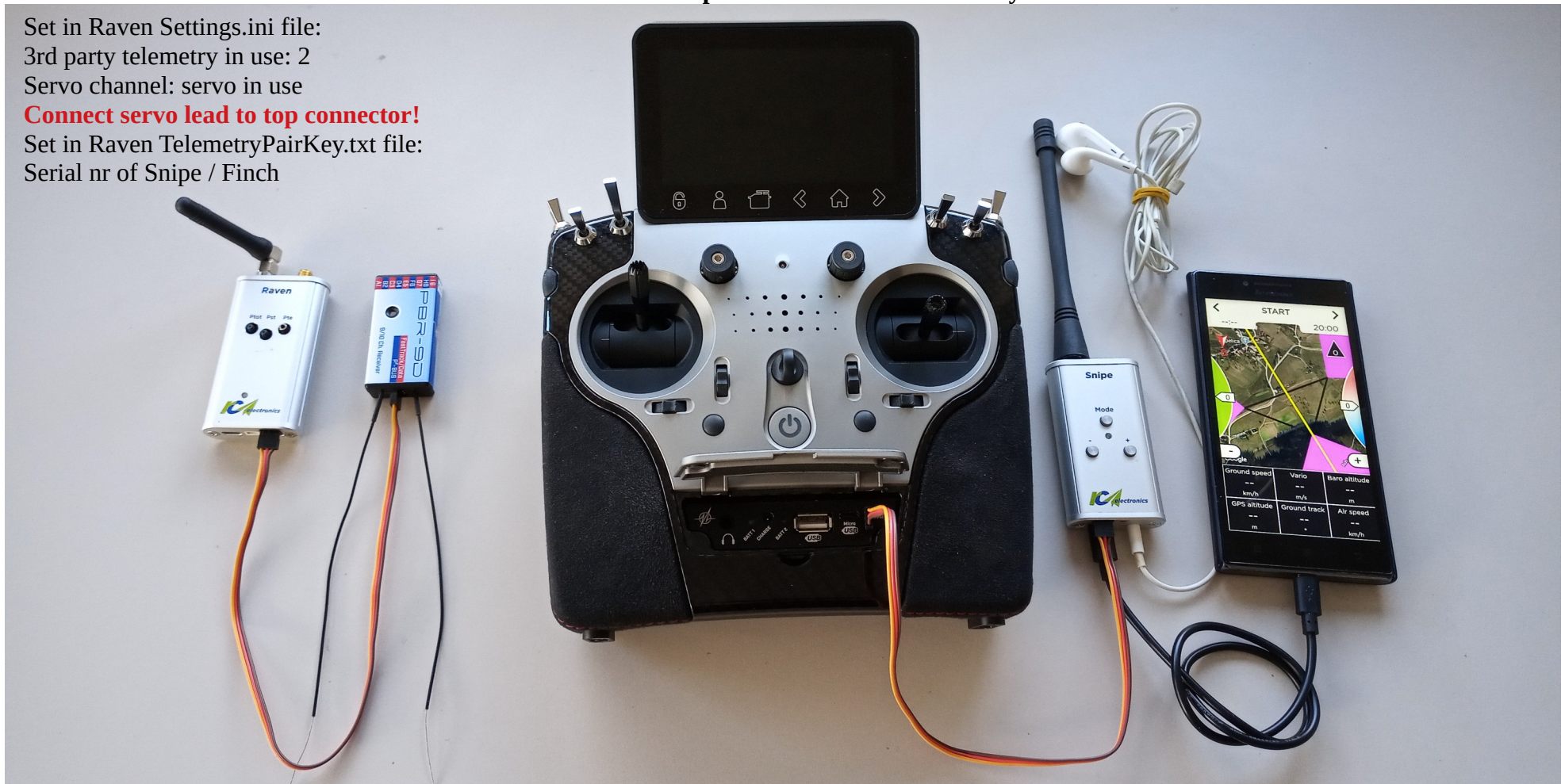
3rd party telemetry in use: 2

Servo channel: servo in use

Connect servo lead to top connector!

Set in Raven TelemetryPairKey.txt file:

Serial nr of Snipe / Finch



Graupner as primary link + Albatross

Works for all classes.

Graupner can also be used as 2nd link in case of Snipe as ground unit. Look at example of Core/Jeti as 2nd link

Swift is used as example on picture, but Sparrow or Raven can be used also.

Finch can be replaced with Snipe to get stereo audio navigation

Vario **compensated** / **non compensated** (depends if TEK sensor is used): On Core audio or /and on Albatross

Stereo navigation: yes if Snipe is used instead of Finch

Voices: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no (yes in case of Raven + Snipe)**

Servo control in Albatross: yes

Polar measurement: yes

Airspeed indicator in Albatross: yes in case of Raven



Set in Swift Settings.ini file:

3rd party telemetry in use: 4

Servo channel: -1

Connect servo lead to bottom connector from one free servo channel.